

SmartLink MX

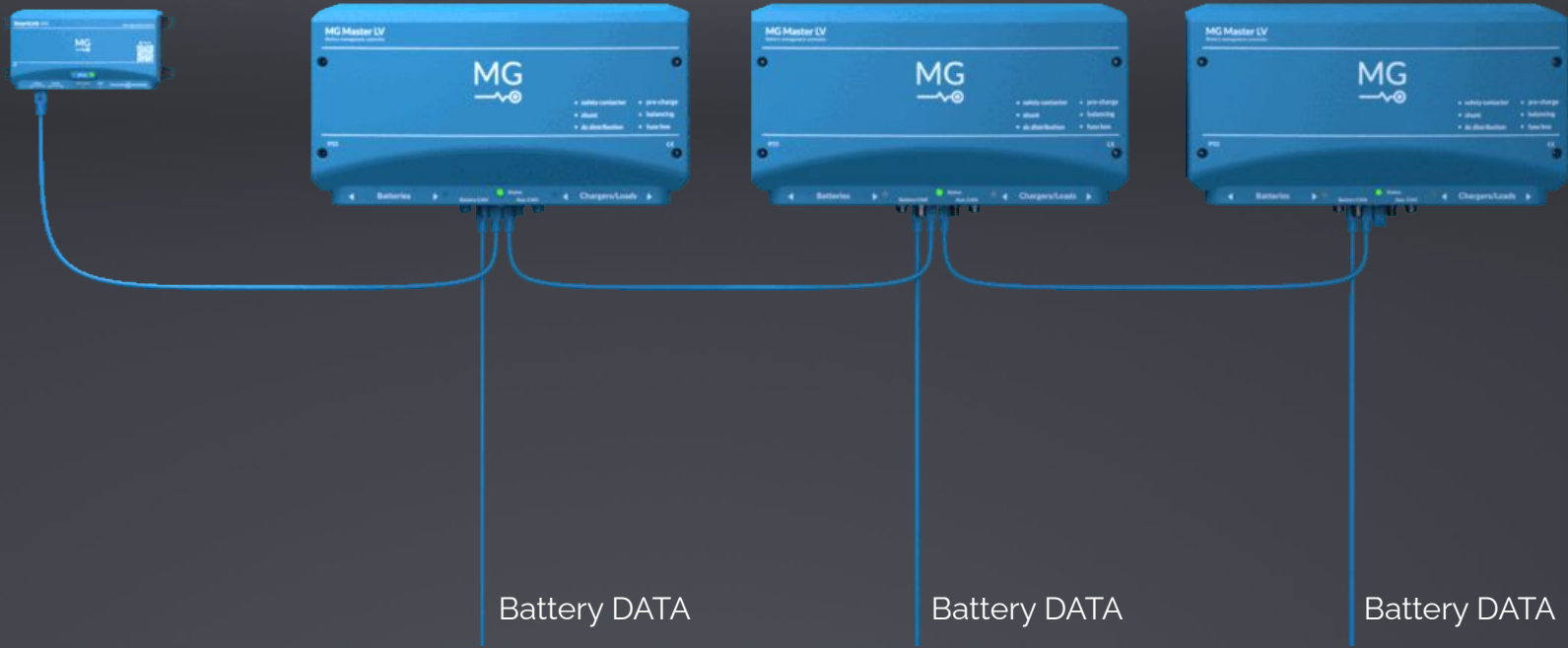
MG





Product Features

Battery-Data Combiner



System Control

System Start

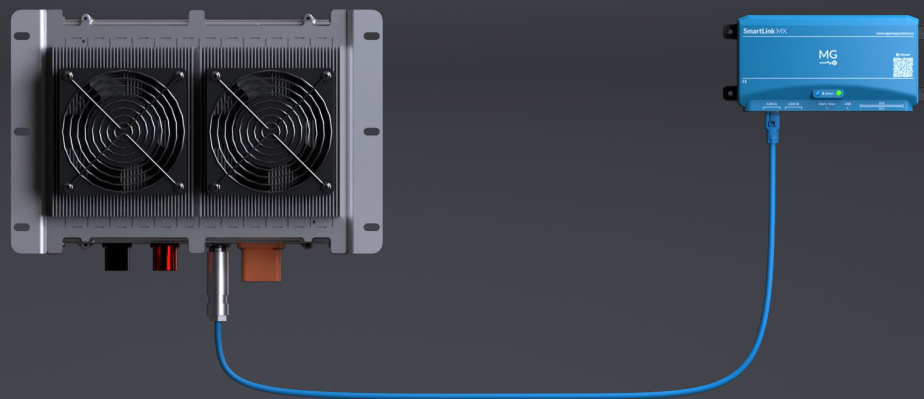


System Control

System Reset/Stop



Charger Control



Combined I/Os

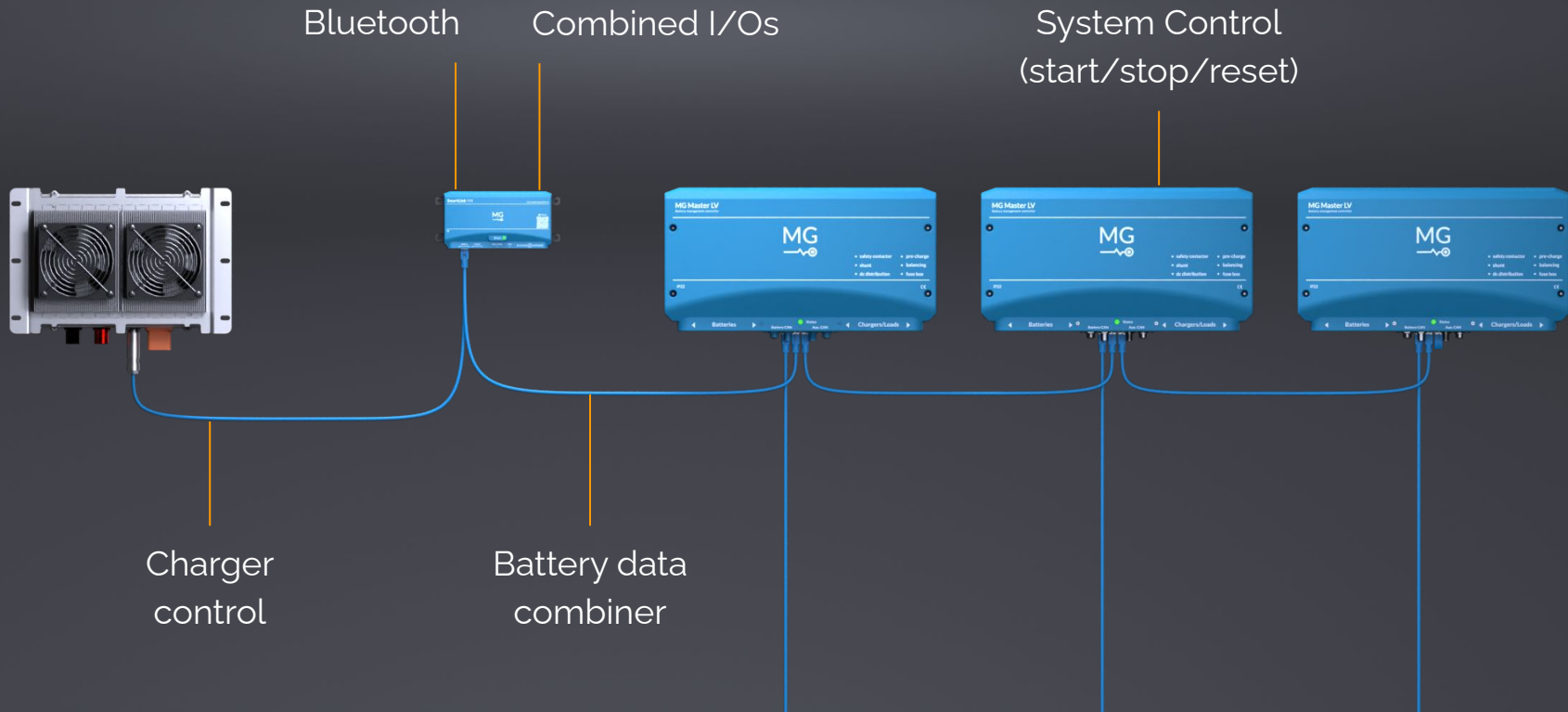
Centralized ATC and ATD



Bluetooth



Function Overview

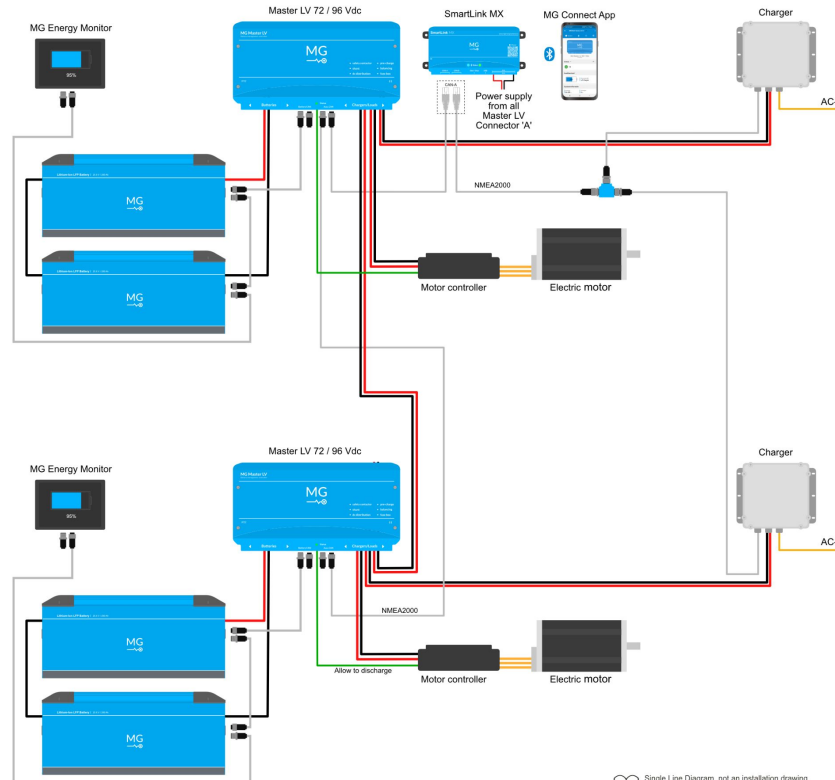


Coming Features

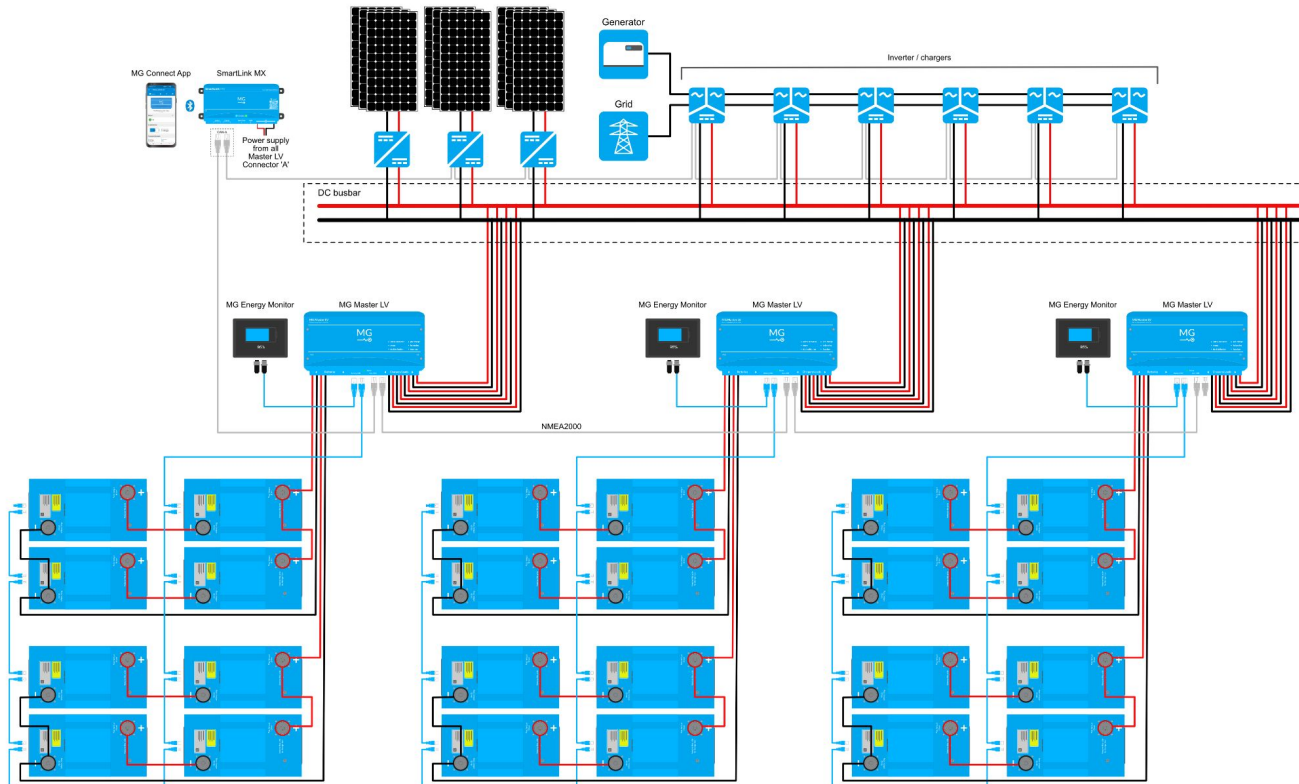
- Second CAN-Bus (MG Energy Monitor)
- Robust Charger (max 6)



Marine System Example



ESS System Example

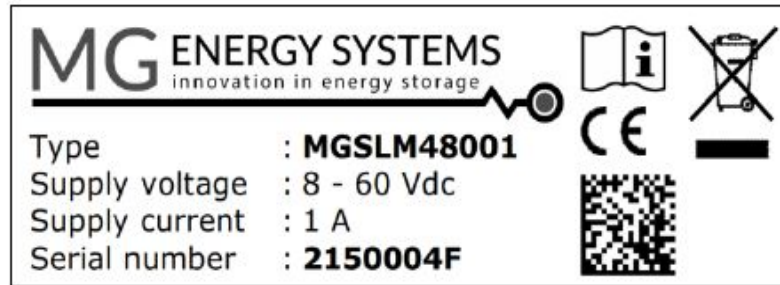


What's in the Box?

- MG SmartLink MX
MGSLM48001
- 2x Connector Terminal Block Plug 1x6 5.08mm
MG5000230
- 1x RJ45 terminator (bag of 2)
MGRJ45000010



Identification Label



Front



Status LED



Off

No Power (Device is never sleeping)

Short on, Long off

Searching for BMS

50/50

Waiting for start command

Long on, Short off

Pre-charging

On

System running/waiting for running

Bottom

- A CAN-A – 2x RJ45: NMEA2000 connection
- B CAN-B – 2x RJ45: MG proprietary CAN-Bus
- C Start/Stop/Reset Button
- D USB interface (Upcoming)
- E I/O connector



I/O Connectors



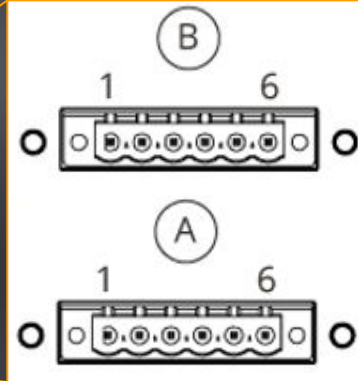
I/O B

Digital relay contact outputs

I/O A

Power supply and digital I/Os

I/O Connectors



Connector pins and specifications					
Conn.	Pin	I/O	Voltage	Current	Purpose
B	1	Out	Max. 60 VDC	0,8 A @ 60 VDC	Programmable output 1
	2				
	3	Out	Max. 60 VDC	0,8 A @ 60 VDC	Programmable output 2
	4				
	5	Out	Max. 60 VDC	0,8 A @ 60 VDC	Programmable output 3
	6				
A	1	In	60 V MAX	1 A	Power input
	2	Out	Power input	0,5 A @ 12 VDC	Programmable output
	3	In	60 V MAX		Programmable input
	4	In			External start button
	5	Out	5 VDC	10 mA	External status output
	6	-			GND



Installation

BMS Settings

Change settings in the BMS (Master LV or HV):

- **External CAN bus protocol: MG NMEA2000**
- **Combined battery mode: ENABLE**

Restart the BMS(s) after these changes



NMEA CAN-Bus

Connect to the **CAN-A** connectors using a RJ45 network cable



If it is the last device in the Bus, make sure to use a **RJ45 terminator** to end the bus

Powering SmartLink MX



I/O - connector A:
Ground (pin 6)
Power input (pin 1)

Operation

Wakeup BMS's

1. Apply settings to BMSs
2. Turn on all BMSs
3. SmartLink MX detects all BMSs
4. SmartLink MX detects system state



System Start

Hold start/stop button for 2 seconds

The system will:

- Pre-charge the DC bus
- All BMS's will close the contactor
(when in a safe voltage window of 0.6% of the system voltage for 10 seconds)



System Stop

Hold start/stop button for 2 seconds

All connected BMS's will:

- Open their contactor at the same time
(No more DC power on the charger/load side)
- Automatically go to standby



SmartLink MX Tool

SmartLink MX Tool

Requirements

- Laptop/PC (\geq Windows 7)
- A USB to CAN-Bus interface.

Supported interfaces:

MG USB-CAN (article number: MGUSBCAN001)

Kvaser (Kvaser Leaf Light HS v2 M12 USB CAN Interface: MGUSBCAN002)

PEAK-system PCAN-USB

- RJ45 Cable

for connection with the SmartLink MX (only with MG USB-CAN)



SmartLink MX Tool



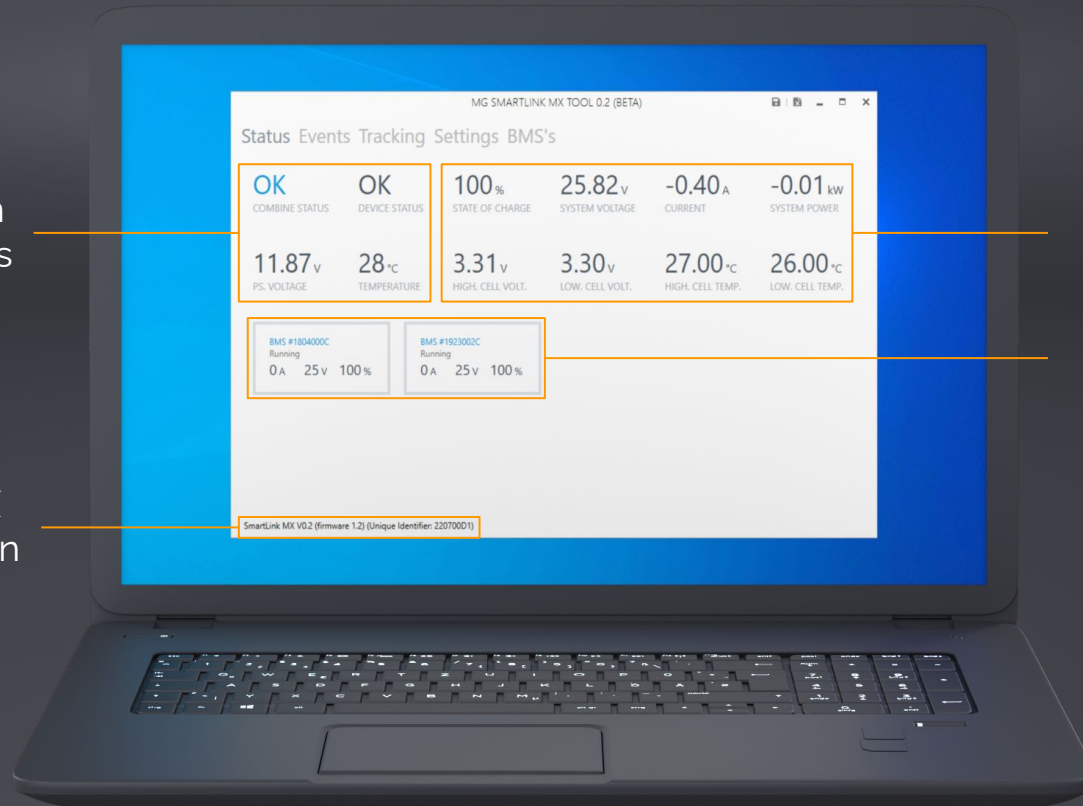
Status Screen

Device information
and combine status

Overview of
combined data

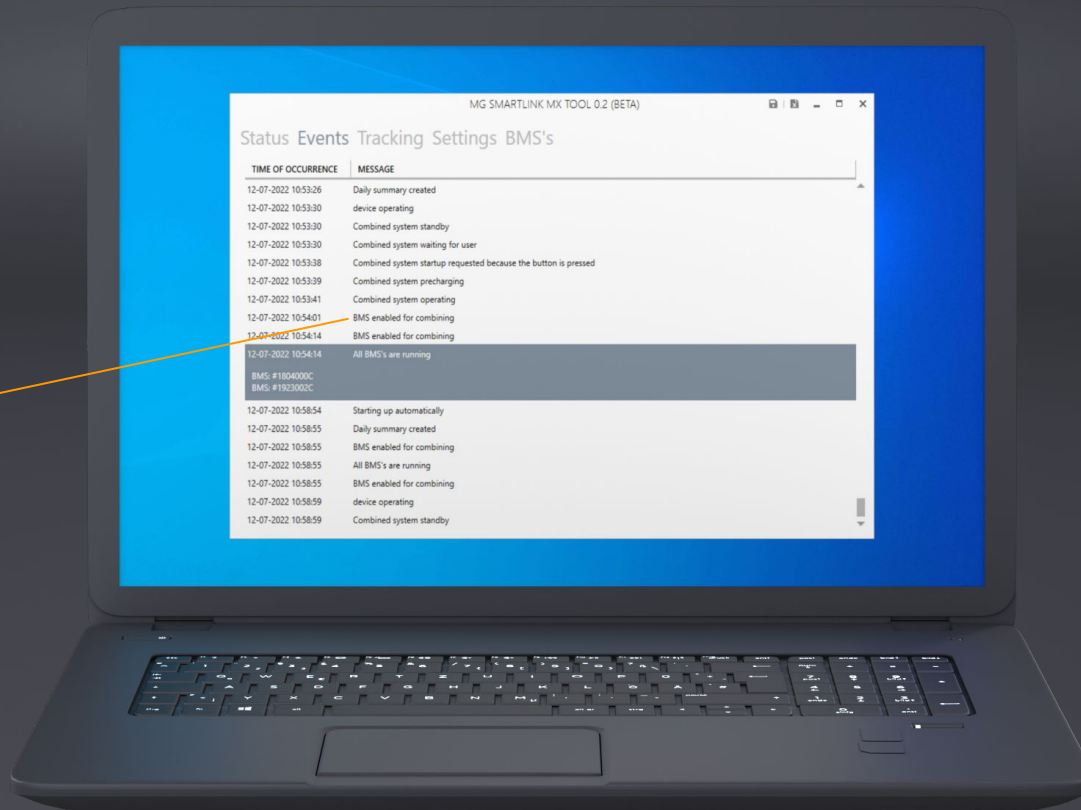
BMS detailed
information

MG SmartLink MX
detailed information



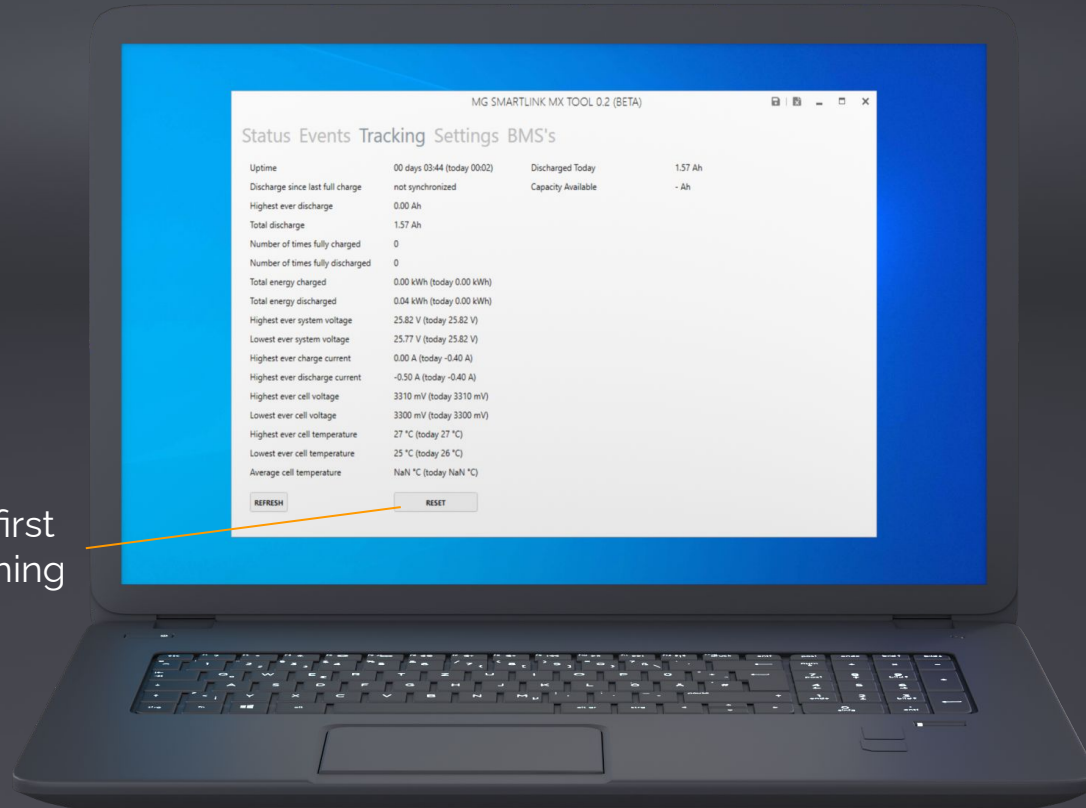
Events Screen

Save the events
Right mouse-click:
"save to file"

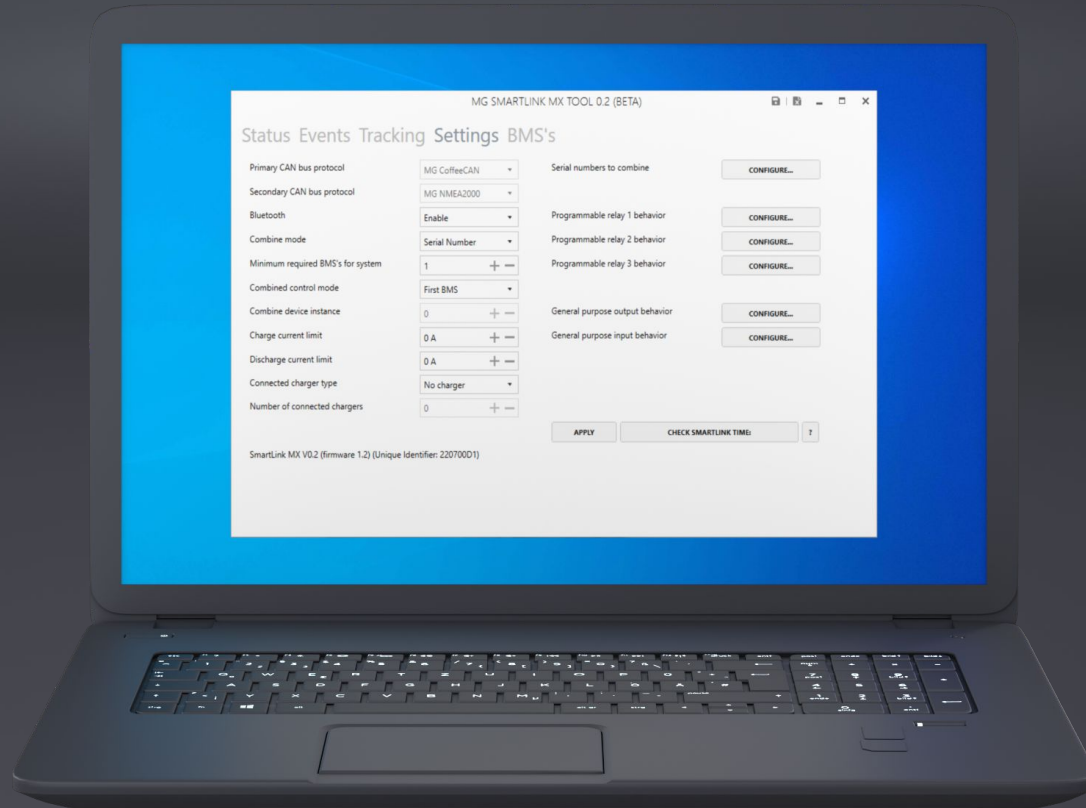


Tracking Screen

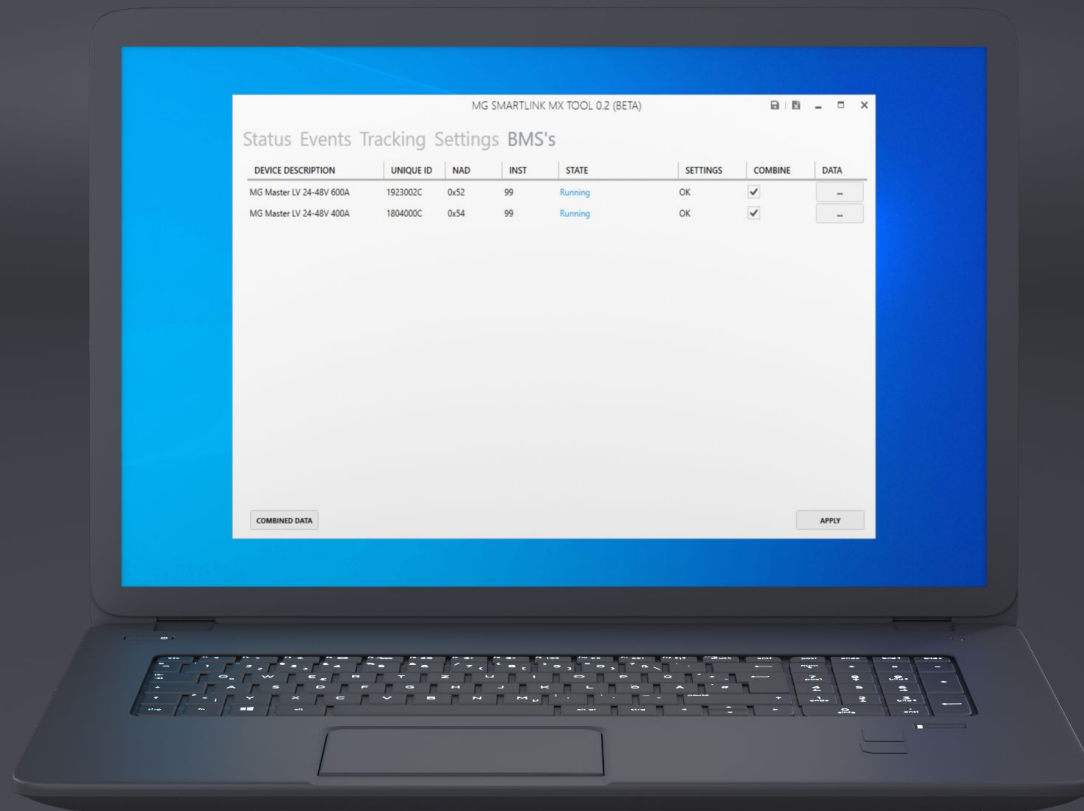
Click Reset at the first system commissioning



Settings Screen



BMS's Screen



SmartLink PLC

SmartLink PLC

- Same functions SmartLink MX
- MOD-Bus TCP
- Certified hardware (class type approval)



SmartLink Impression

